

METHOD AND DEVICE FOR SIGNALING INFORMATION RELEVANT  
FOR THE OPERATION OF A MOTOR VEHICLE

Background Information

The present invention is directed to a method and a device for signaling information relevant for the operation of a motor vehicle according to the definition of the species in the independent claims.

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Methods and devices for signaling information relevant for the operation of a motor vehicle are already known. A visual consumption indicator, for example, is standard in many vehicles and encourages awareness of economical driving. The visual consumption indicator displays the instantaneous fuel consumption value. In this way, different fuel consumption values may be visually displayed on the consumption indicator.

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The driver's driving manner represents a great potential for fuel savings. Most drivers are not aware of the physical causes for high consumption, or information is lacking which is necessary for optimum driving, the instantaneous engine efficiency for example.

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Advantages of the Invention

The method and device according to the present invention for signaling having the features of the independent claims have the advantage over the related art that information relevant for the operation of the motor vehicle is formed by an operating point of a drive unit of the vehicle, and that, as a function of the operating point, a haptic signal is formed at a control element of the vehicle, an accelerator pedal in particular. Information about fuel consumption-minimizing driving may be conveyed to the driver in this way. In addition, the haptic signal on the control element has the advantage that the driver does not have to avert his/her eyes from the roadway. As a result, the driver is not distracted from traffic. Therefore, the haptic signal does not represent a safety risk and does not increase the risk of an accident. If the control element is one which the driver constantly operates, for example the accelerator pedal, it is also ensured that the driver is able to constantly monitor information about the drive unit's operating point. If the control element is the accelerator pedal, the haptic signal

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of the drive unit's operating point may, via the accelerator pedal, directly prompt the driver to drive in a fuel consumption-minimizing manner by changing the accelerator pedal position, thus causing a change in the haptic signal.

5 Advantageous refinements of and improvements on the method recited in the main claim are made possible by the measures listed in the subclaims.

It is particularly advantageous if an optimum operating point of the drive unit, optimum engine efficiency in particular, is indicated by the haptic signal. The driver is enabled in this  
10 way to drive or to accelerate with optimum engine efficiency or an optimum operating point of the drive unit, thus minimizing fuel consumption.

It is particularly advantageous if haptic signaling starts approximately when the optimum operating point is reached. In this way, the driver may very precisely adapt his/her driving  
15 manner to the optimum operating point of the drive unit and may thus operate the vehicle with minimized fuel consumption. If the control element is designed as an accelerator pedal, the driver may then directly use the information about the optimum operating point for his/her driving manner by constantly driving within the range of the occurring haptic signal at the accelerator pedal.

20 It is particularly advantageous if the haptic signal is formed via a restoring force acting on the control element. It is ensured in this way that the driver notices the haptic signal when operating the control element. Furthermore, if the control element is designed as an accelerator pedal, driving with the optimum operating point of the drive unit is made easier  
25 for the driver. The restoring force, occurring when the optimum operating point is reached, makes it easier for the driver to maintain the optimum operating point of the drive unit during operation of the accelerator pedal.

#### Drawing

30 An exemplary embodiment of the present invention is illustrated in the drawing and explained in greater detail in the following description.

Fig. 1 shows a block diagram including the device according to the present invention,

Fig. 2 shows a characteristics map for determining a specific fuel consumption of a motor vehicle,

Fig. 3 shows a characteristics map for determining a restoring force for an acceleration pedal of the vehicle, and

- 5 Fig. 4 shows a function chart for demonstrating the operating mode of the device and method according to the present invention.

### Description of the Exemplary Embodiments

In Figure 1, reference numeral 25 indicates a controller of a motor vehicle having a drive unit  
10 which may include, for example, a gasoline engine, a diesel engine, an electric motor, or the like, or which is based on any other alternative drive concept. Furthermore, the vehicle includes a control element 1, which is designed as an accelerator pedal for example.

Controller 25 includes a driver intent interpretation unit 30 which is connected to accelerator pedal 1. From position wped of acceleration pedal 1 operated by the driver, driver intent

15 interpretation unit 30 determines a setpoint value of an output variable of the drive unit. This output variable may be, for example, an engine output torque, or a wheel output torque, or an output power, or an output variable derivable from the mentioned variables. It should be assumed in the following that the output variable of the drive unit is an engine output torque.

In a manner known to those skilled in the art, driver intent interpretation unit 30 thus forms a

20 setpoint value  $M_{ENGsetpoint}$  for the engine output torque of the drive unit from position wped of accelerator pedal 1. Setpoint value  $M_{ENGsetpoint}$ , formed as a function of the driver's intent, is supplied to a first adding element 35 and added there to a resulting torque request  $M_{other}$

which is formed by a coordinator 40 as a function of the other torque requests. The other torque requests may be initiated, for example, for compensating the torque demands of

25 vehicle auxiliaries, such as an air conditioning system, a car radio, a servo motor, or an idling regulation. Coordination of these other torque requests in coordinator 40 also takes place in a manner known to those skilled in the art. The sum formed by first adding element 35 is a

resulting total setpoint value  $M_{setpointtotal}$  which is supplied to a device 5 according to the present invention. Device 5 is used for haptic signaling at control element 1, acceleration

30 pedal 1 in this example. This haptic signaling may take place by generating a suitable restoring force at accelerator pedal 1, for example. An instantaneous speed  $n_{ENG}$  of an engine

driving the drive unit, which may be as described a gasoline engine, a diesel engine, or an

electric motor, is supplied to device 5 by an engine speed sensor 45. A coordinator 50 for other restoring force requests on accelerator pedal 1 may optionally be provided and forms a resulting restoring force request  $F_{fb\text{other}}$  for these other restoring force requests. This could be, for example, a haptic response for maintaining a safety distance. Resulting restoring force request  $F_{fb\text{other}}$  is also supplied to device 5. In addition, an input unit 15, indicated in Figure 1 in dashed form, may also be optionally provided. For example, the driver may preselect one or multiple fuel consumption values at input unit 15. These values are also supplied to device 5. According to Figure 1, controller 25 includes driver intent interpretation unit 30, first adding element 35, and device 5. Controller 25 may be implemented, for example, in the form of hardware and/or software, the software being able to be executed by a microchip.

Device 5 determines a resulting total restoring force  $F_{fb\text{total}}$  from the supplied input variables and controls accelerator pedal 1 for setting this resulting total restoring force  $F_{fb\text{total}}$ . This may be implemented in a manner known to those skilled in the art via an actuator (not shown in Figure 1), which is electronically controlled by device 5, for setting a spring force which acts against the operating direction of accelerator pedal 1.

As an example, it should be assumed in the following considerations that the vehicle is driven by an internal combustion engine, i.e., a gasoline engine or a diesel engine for example. However, the considerations are generally directed at the vehicle's power consumption. During acceleration, the fuel consumption corresponds to the power necessary for overcoming the vehicle's mass inertia. The fuel consumption during acceleration may be minimized in that the engine is held at the most favorable operating point by the driver using a defined accelerator pedal position; according to the present invention, this accelerator pedal position should be indicated to the driver via a haptic signal at accelerator pedal 1.

Figure 2 shows what is known as a shell characteristics map of an internal combustion engine in which the engine's output torque, indicated torque  $M_i$ , is applied in Nm above the engine speed  $n_{\text{ENG}}$  in U/min. Indicated torque  $M_i$  and engine speed  $n_{\text{ENG}}$  establish a characteristics map for a specific fuel consumption of the vehicle in g/kWh in which isolines for this specific fuel consumption are indicated in the indicated unit. The characteristics map may be determined on an engine test bench in that, by predefining engine speed  $n_{\text{ENG}}$  and the load, which is implemented, for example, using an eddy-current brake which is connected to the engine's crankshaft, the ratio from the consumed fuel quantity and performed mechanical

work at the crankshaft is determined. This ratio is referenced as  $Be$ . Ratio  $Be$  is the specific fuel consumption. According to Figure 2, the specific fuel consumption  $Be$  is then applied over the engine speed and indicated torque  $M_i$  which represents the load varied by the eddy-current brake in a manner known to those skilled in the art. Indicated torque  $M_i$  may be determined as a mean value for the respective braking effect of the eddy-current brake over a predefined time. Connecting all points in the characteristics map which have approximately the same specific fuel consumption  $Be$  results, as indicated in Figure 2, in shell-shaped isolines or contour lines for which this characteristics map is named.

For each engine speed  $n_{ENG}$  there is exactly one minimum specific fuel consumption  $Be$  and thus exactly one optimum efficiency. The points with the minimum specific fuel consumption for different engine speeds  $n_{ENG}$  are indicated in Figure 2 by triangles. Connecting the points with the minimum specific fuel consumption to one another results in the dotted line in Figure 2 which is indicated by reference numeral 55. This line 55 is also referred to in the following as the line of the minimum specific fuel consumption. Figure 3 shows a characteristics map in which the curve of a haptic signal  $F_{FB}$  and thus a restoring force for acceleration pedal 1 is applied in  $N$  above engine speed  $n_{ENG}$  in  $U/min$  on the abscissa and indicated engine torque  $M_i$  in  $Nm$  on the ordinate. The curve of this haptic signal  $F_{FB}$  arises from the dotted line 55 of the minimum specific fuel consumption according to Figure 2 in which the areas above and below this line 55 are separated from one another by different values of restoring force  $F_{FB}$ . In particular, these values may be two different values, namely a first restoring force  $F_1$  above line 55 of the minimum specific fuel consumption and a second restoring force  $F_2$  below this line 55, first restoring force  $F_1$  being able to be greater than second restoring force  $F_2$  and second restoring force  $F_2$  being able to be equal to zero, for example. This makes it possible to signal to the driver, via an increase in restoring force  $F_{FB}$  at accelerator pedal 1, the optimum operating point of the drive unit and thus the optimum engine efficiency. In the event that, as described, first restoring force  $F_1$  is greater than second restoring force  $F_2$  and second restoring force  $F_2$  is equal to zero, the optimum engine efficiency occurs for the accelerator pedal position at which the driver, while operating accelerator pedal 1, notices a corresponding increase in the resistance and thus in the restoring force.

Figure 4 shows a function chart for demonstrating the operating mode of device 5 according to the present invention and the method according to the present invention. In Figure 4, the

same reference numerals indicate the same elements as in Figure 1. In contrast to the block diagram in Figure 1, the configuration of device 5 according to the present invention is additionally explained in greater detail in Figure 4. Device 5, which, for example, may be implemented as a software structure on a microchip, includes a characteristics map function 5 60 which implements the shell characteristics map from Figure 2 and to which resulting total setpoint torque  $M_{\text{setpointtotal}}$  released from adding element 35 and instantaneous engine speed  $n_{\text{ENG}}$  are supplied as input variables. Hence, characteristics map function 60 determines haptic signal  $F_{\text{FB}}$  as an output variable in that a check is performed to determine whether the operating point, formed by instantaneous engine speed  $n_{\text{ENG}}$  and resulting total setpoint torque 10  $M_{\text{setpointtotal}}$ , is above or below line 55 of the minimum specific fuel consumption. If the operating point is above line 55 then  $F_{\text{FB}}$  equals  $F_1$ , otherwise  $F_{\text{FB}}$  equals  $F_2$ . Haptic signal  $F_{\text{FB}}$  is supplied to a maximum selector element 65 to which the resulting restoring force request  $F_{\text{fbother}}$  of the other restoring force requests is additionally supplied by restoring force coordinator 50. Maximum selector element 65 selects the maximum from the supplied 15 variables and releases it as resulting haptic signal  $F_{\text{fbtotal}}$  to accelerator pedal 1 for setting the respective restoring force. Using maximum selector element 65, the restoring force at accelerator pedal 1 is limited to the downside to ensure that, after release, the accelerator pedal returns to its original position.

20 The method according to the present invention and device 5 according to the present invention make it possible for the driver, due to the haptic signal at accelerator pedal 1, to accelerate and to run the engine with optimum efficiency. In addition, in contrast to a visual indicator, a haptic signal at accelerator pedal 1 is constantly present in the driver's awareness, is not irritating, and does not distract from traffic.